
Personal authentication using hand- geometry and palmprint features – the state of the art

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Introduction

Human hand contains a wide variety of measurable characteristics that can be used by biometric authentication systems.

E.g.,

- **shape, palmprint, fingerprint**
on the palmar surface of the hand and
- **shape, veins**
on the dorsum of the hand.



Introduction – Cont.

Hand characteristics are typically acquired by a sensor that captures visible light.

E.g., visible images of **palmar** (a), **lateral** (b) and **dorsal** (c) surface of the hand are displayed on the bottom of the slide.

a)



b)



c)



Introduction – Cont.

The visible image of the **palmar surface** of the hand is typically acquired by:

- a **scanner** rated at >100 dots per inch (dpi)/256 grey levels or by
- a **low/medium/high-resolution CCD camera**, located under the transparent platform where the hand is placed.



Introduction – Cont.

The visible images of the **lateral and dorsal surfaces** of the hand are captured with

- a **low-resolution CCD camera** placed above the platform with a side-mounted mirror inclined at 45° to the platform.

There are usually **4–6 pegs** on the platform to guide the placement of the user's hands.

E.g.,

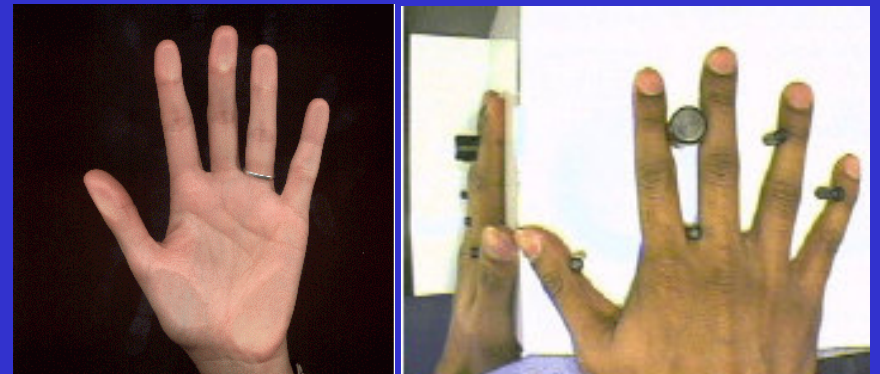
Jain et al. [1999]:



Introduction – Cont.

From visible images of the **palmar, lateral and dorsal surfaces** of the hand 3 classes of biometric features can be extracted:

1. **hand-geometry features**, (e.g., width, thickness and area of the palm, lengths, widths and thickness of fingers),
2. **palmprint features** (e.g., principle lines, wrinkles, ridges, texture), and
3. **fingerprint features** (e.g., minutiae locations, types, number).



Hand-geometry-based systems

Hand-geometry features are usually extracted from visible images of **lateral** and **dorsal** surface of the hand.

Several prototypal hand-geometry-based authentication systems have been proposed.

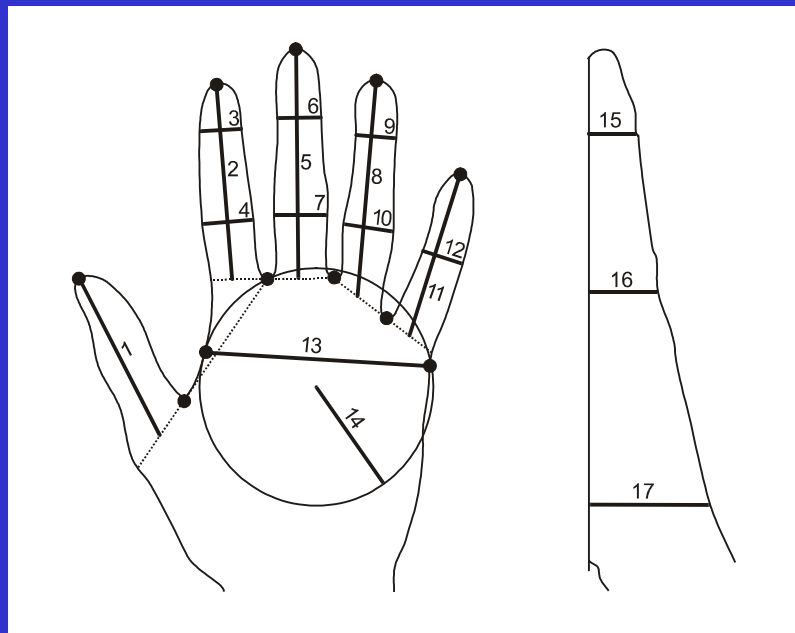
E.g., by:

- ***Golfarelli et al. [1997]***
- ***Jain et al. [1999]***
- ***Sanches-Reillo et al. [2000]***

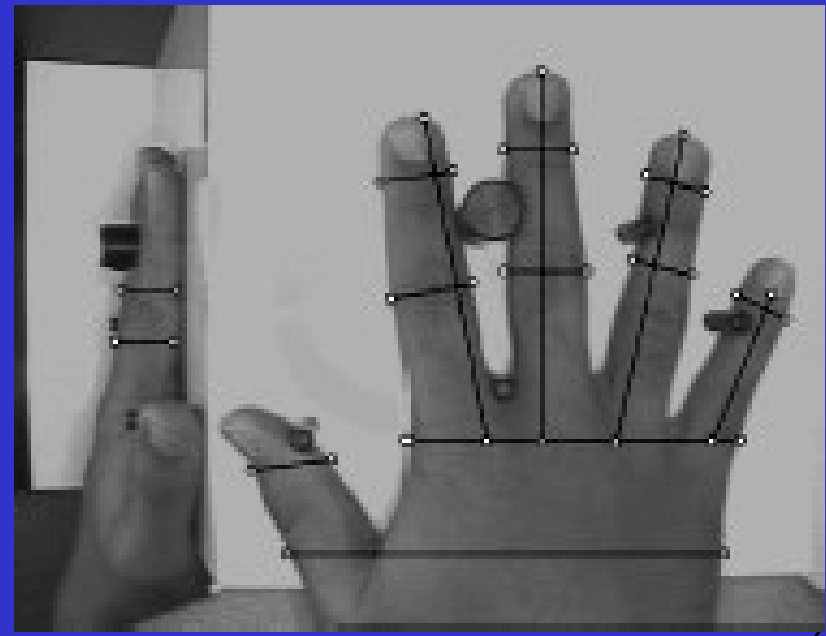


Hand-geometry-based systems

- *Golfarelli et al.* : 17 hand-geometrical features (see image), Bayes classification rule
- *Jain et al.* : 16 hand-geometrical features (see image), 1-NN classification rule (4 distance metrics)



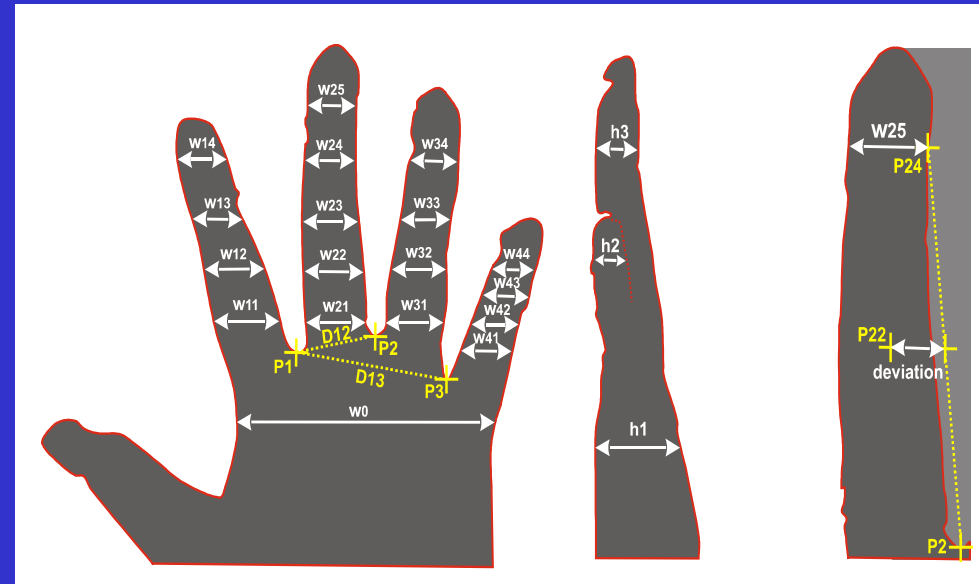
Golfarelli et al.



Jain et al.

Sanches-Reillo et al. - Features

- *31 geometrical features:*
 - 21 widths,
 - 3 heights,
 - 4 deviations, and
 - 3 angles,



are extracted from the contour image of the lateral and dorsal surfaces of the hand.

After a discriminatory analysis of features, the number of features is reduced to 25.

Sanchez-Reillo et al. - Classification

Authentication experiments are made by use of:

- 1-NN classification rule (Euclidean and Hamming distance),
- Gaussian Mixture Models (GMMs), and
- Radial Basis Function Neural Networks (RBF).

The system was trained and tested using a database of 200 images of 20 people

Sanches-Reillo et al. - Results of classification tests

		d_E	d_H	GMMs	RBF
Number of enrolment vectors (25 features)	3	86%	75%	88%	90%
	4	85%	82%	93%	91%
	5	86%	87%	96%	91%
Feature vector size (5 enrolment vectors)	25	86%	87%	96%	91%
	21	84%	86%	97%	95%
	15	86%	88%	96%	89%
	9	77%	75%	91%	82%

Sanchez-Reillo et al. - Results of verification tests

In verification experiments 5 enrolment vectors per user are used

- Best results are obtained using GMMs (EER \approx 5%)
- Results are similar for 25, 21 and 15 features in feature vectors.

Commercial hand-geometry-based systems

- Hand-geometry-based verification systems are predominantly manufactured by **Recognition Systems, Inc.** (<http://www.recogsys.com/index.shtml>)
- Products: **HandKey ID3D** and **HandKey II**



Commercial two-finger geometry-based system

- **BioMet Partners Inc.** (<http://www.biomet.ch>) manufactures two-finger geometry verification systems
- Products: **VeryFast** and **FingerFoto**



Palmprint-based systems

Palm-print features are usually extracted from visible images of **palmar** surface of the hand.



palm - the inner surface of the hand between the wrist and the fingers

Palmprint-based systems – Cont.

Recently, the problem of personal authentication using palmprint features has drawn considerable attention and several prototypical palmprint-based authentication systems have been proposed.

E.g., by:

- ***Zhang et al. [1999]***
- ***Duta et al. [2002]***
- ***You et al. [2002]***
- ***Li et al. [2002]***

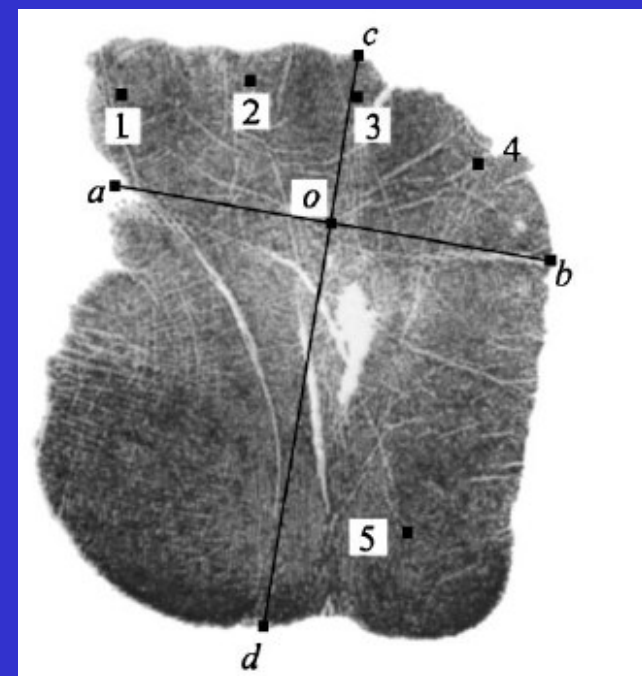
Palmpoint-based systems – Cont.

- *Han et al.* [2003]
- *Ying-Han et al.* [2003]
- *Lu et al.* [2003]
- *Kong et al.* [2003]
- *Zhang et al.* [2003]
- *Wu et al.* [2003]

Palmprint-based systems - Features

The most important features of a palm are:

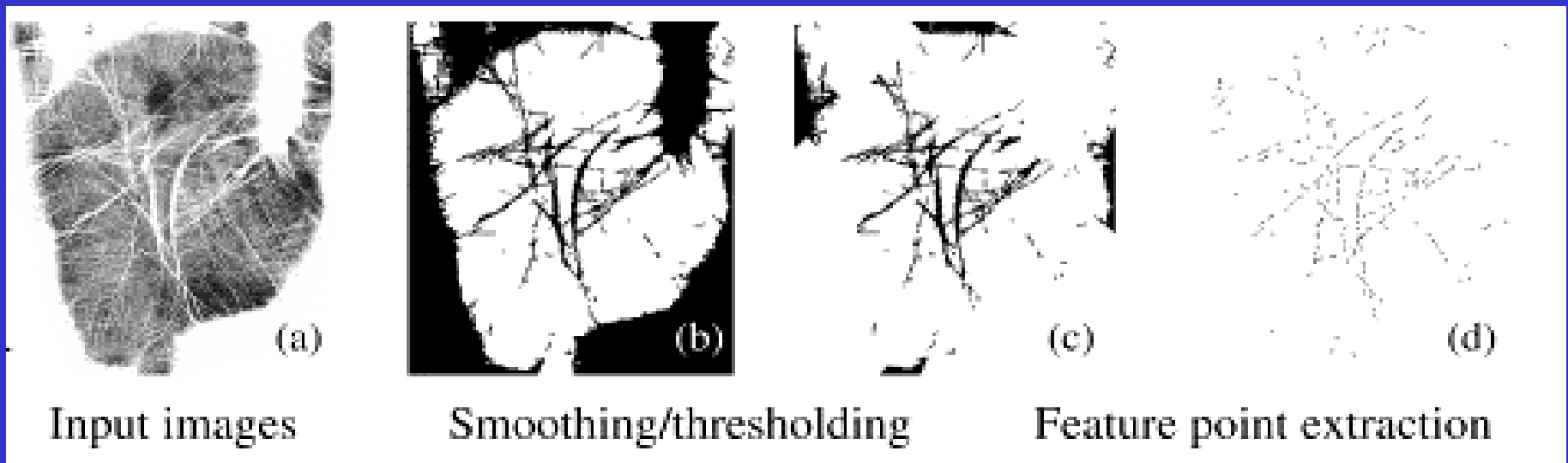
- **Geometry features:** width (a-b), length (c-d) and area of a palmprint
- **Principal lines-based features:** lines endpoints (a, b), their midpoint (o)
- **Delta point-based features:** centers of delta-like regions in a palmprint (points 1-5) (see image)



(Zhang et al.)

Palmprint-based systems -Features

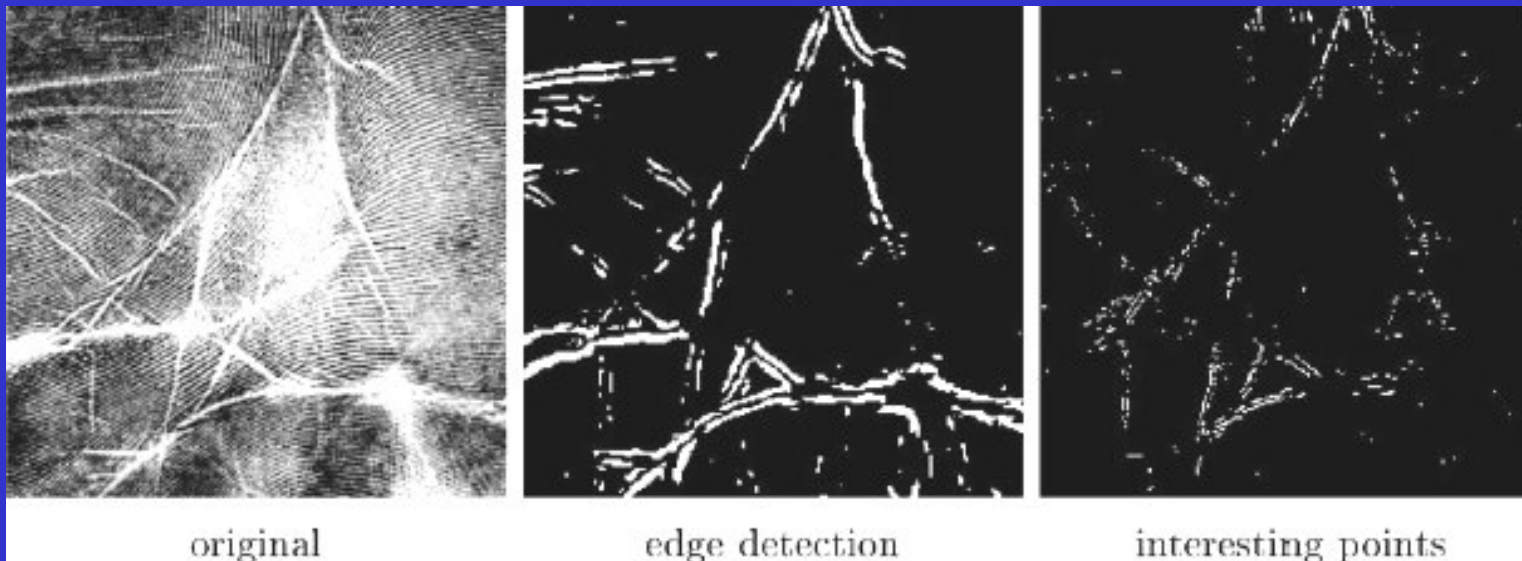
- **Wrinkle features:** Thin and irregular lines and curves different from principal lines
- **Minutiae features:** Significant feature measurement of ridges existing in a palm.
- **Feature points/orientations along prominent palm lines** (see image)



(Duta et al.)

Palmprint-based systems - Features

- **Texture:** local texture energy, standard deviation
- **Moments:** Zernike, pseudo Zernike and Legendre moments
- **Interesting points** (see image)



(You et. al.)

Palmprint-based systems - Features

- **Coefficients and functions of transforms:** Fourier, Karhunen-Loeve, Fisher's linear discriminant, *Gabor filters*

E.g., Fourier transform (*Li et al.*)

Li et al. [2002]



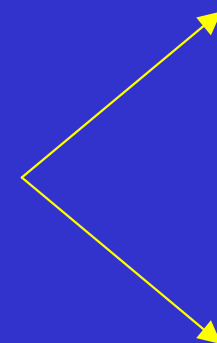
palmprint



ROI



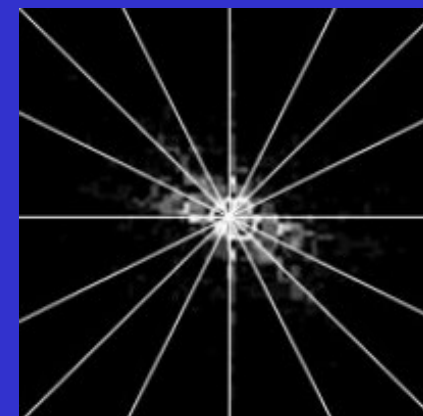
ROI in freq.
domain



R - features



Θ - features



Palmprint-based systems – Classification & Results

Authentication experiments are made by use of:

- 1-NN classification rule (Hamming, Euclidean, weighted Euclidian and Hausdorff distance, correlation),
- Backpropagation neural network

Systems were trained and tested with databases containing from 30 to 3056 palmprints

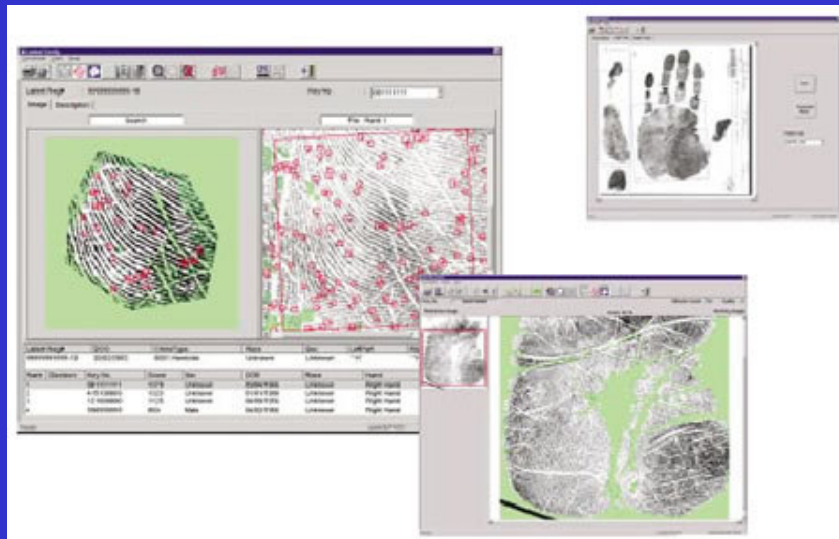
- Recognition rates reported: 95% to 99,75 %
- Equal Error Rate (ERR) < 1%

Commercial palmprint-based systems

The latest generation of automated fingerprint identification systems (AFIS) by NEC and MOTOROLA

- **Automated PalmPrint™ System**
(http://www.necsam.com/idsolutions/products/law_enforcement.cfm)
- **Omnitrak™ AFIS/Palmprint Identification Technology**
(<http://www.motorola.com/LMPS/RNSG/pubsafety/40-70-10.shtml>)

include modules for palmprint identification.



Systems based on the fusion of palmprint and hand-geometry features

A high-resolution sensor of a visible image of the palmar surface of the hand can **simultaneously** capture

- hand-geometry,
- palmprint, and
- fingerprint

features of the hand.



Systems based on the fusion of palmprint and hand-geometry features – Cont.

Since the palmprint and hand-geometry features can be extracted from the same image, the **performance** and **robustness to the fraudulent technologies** of a hand-based authentication system can be **easily increased** by integrating palmprint and hand-geometry features.

Systems based on the fusion of palmprint and hand-geometry features – Cont.

Systems based on the fusion of **palmprint** and **hand-geometry** features have been proposed by:

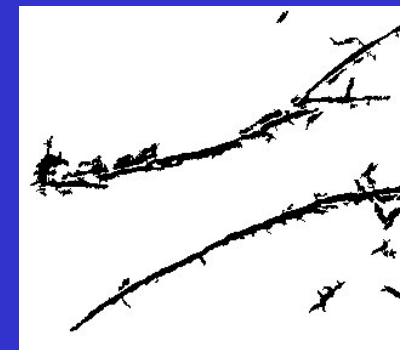
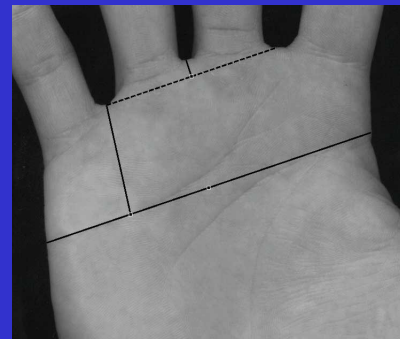
- *Ribaric et al.* [2002]
- *Kumar et al.* [2003]

Ribaric et al. - Features

- 20 finger-geometry features,
- 4 hand-geometry features, and
- 399 palmprint features

are fused at **decision level**.

The system was trained and tested using a database of 555 images of 111 people



Ribaric et al. – Results of verification tests

	FAR	FRR
FG	0%	5.2%
PG	32.6%	27.7%
P	8.1%	6.1%
FG-PG	0%	4.6%
PG-P	2.6%	2.3%
FG-P	0%	1.8%
FG-PG-P	0%	1.7%

FG, PG and P denote finger-geometry, palm-geometry and palmprint features, respectively.

Kumar et al. - Features

- 16 hand-geometry features (4 finger lengths, 8 finger widths, palm width, palm length, hand area, and hand length) and
- n palmprint features

are fused at

- **feature-generation level** and at
- **decision level.**

The system was trained and tested using a database of 472 images of 100 people

Kumar et al. – Results of verification tests

	FAR	FRR	Threshold
Palmprint	4.49%	2.04%	0.9830
Hand-geometry	5.29%	8.34%	0.9314
FGL	5.08%	2.25%	0.9869
FDL	0%	1.41%	0.9840

FGL and FDL denote fusion at feature generation level and fusion at decision level, respectively.

Summary

- Hand-geometry-based authentication systems are attractive because measurements are easily collectible and non-intrusive.

The main drawbacks of such systems are the low uniqueness and accuracy, as well as the low scalability.

Summary

- Palmprint-based authentication systems, due to the uniqueness and permanence of the palmprint features, are considered as **highly accurate and scalable systems**.
- Authentication systems based on fusion of hand-geometry and palmprint features increase the performance and they are generally more robust to fraudulent technologies.

Summary

- For still higher accuracy and scalability, a multimodal authentication system that integrates features which can be extracted from the **palmar surface** images, i.e.:
 - hand-geometry,
 - palmprint and
 - fingerprintfeatures is proposed to be developed.
- All these features can be obtained from only **one high-resolution single-shot image**.

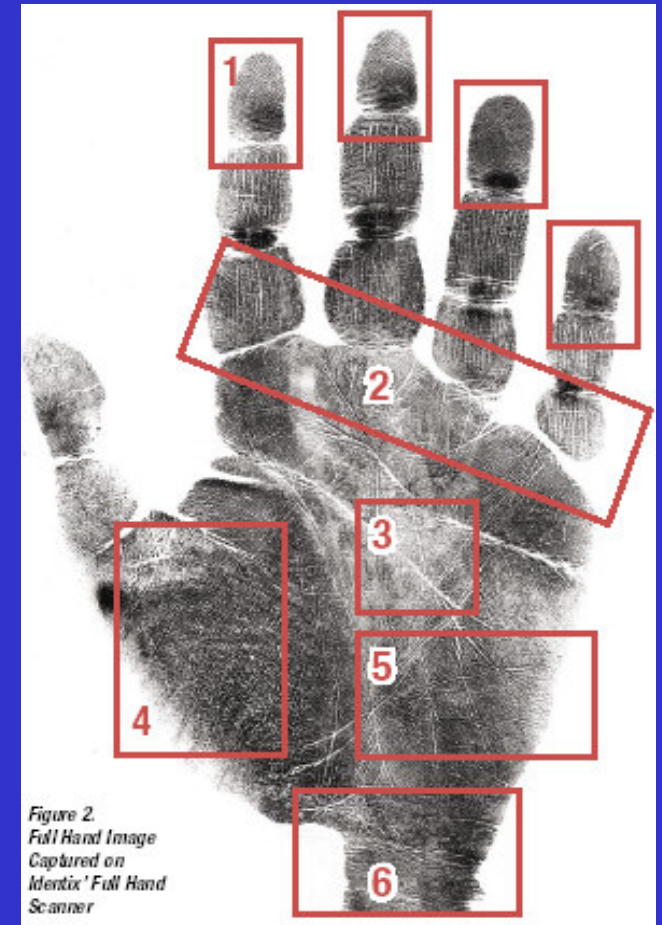
E.g.,

from the image captured with
TouchPrint™ 3800 Full Hand
Scanner by Identix, Inc.

(<http://www.identix.com/>)

which scans entire palmar surface
of the hand at 1000 dpi resolution.

1. Fingerprints
2. Interdigital region
3. Cup of the palm
4. Thenar
5. Hypothenar
6. Carpal Crease



End of presentation

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Comparison of the human and technical factors of seven popular unimodal biometric systems

H, M, and L denote high, medium, and low, respectively.

	Fingerprint	Face	Hand geometry	Palmprint	Iris	Voice	Signature
Universality	M	H	M	M	H	M	L
Uniqueness	H	L	M	H	H	L	L
Permanence	H	M	M	M	H	L	L
Collectability	M	H	H	H	M	M	H
Performance	H	L	M	H	H	L	L
Acceptability	M	H	M	M	L	H	H
Circumvention	M	H	M	L	L	H	H
Scalability	H	M	L	H	H	L	H
Maturity	H	M	H	L	M	M	M
Cost	M	L	H	M	H	L	M